

Rotational averaging in the third order Liouville pathways

ad b)

$$\vec{d}_n = d_n \vec{u}_n$$

$$\langle (\vec{d}_1 \cdot \vec{e}_1) (\vec{d}_2 \cdot \vec{e}_2) (\vec{d}_3 \cdot \vec{e}_3) (\vec{d}_4 \cdot \vec{e}_4) \rangle_{\Omega} = ?$$

$$= d_1 d_2 d_3 d_4 \sum_{\substack{i,j,\epsilon,\ell \\ \propto A_j \delta}} \underline{\ell_i^{(1)}} \ell_j^{(2)} \ell_\epsilon^{(3)} \ell_\ell^{(4)} \left\langle I_{ij\epsilon\ell \propto A_j \delta} \right\rangle_{\Omega} u_i^{(1)} u_j^{(2)} u_\epsilon^{(3)} u_\ell^{(4)}$$

($\underline{u_i^{(1)}} u_j^{(2)} u_\epsilon^{(3)} u_\ell^{(4)}$)

$$= d_1 d_2 d_3 d_4 \sum_{i,j,\epsilon,\ell} \ell_i^{(1)} \ell_j^{(2)} \ell_\epsilon^{(3)} \ell_\ell^{(4)} \langle \underline{u_i^{(1)} u_j^{(2)} u_\epsilon^{(3)} u_\ell^{(4)}} \rangle_{\Omega}$$

$$\langle \underline{u_i^{(1)} u_j^{(2)} u_\epsilon^{(3)} u_\ell^{(4)}} \rangle_{\Omega} = A^{(1)} \delta_{ij} \delta_{\epsilon\ell} + A^{(2)} \delta_{i\epsilon} \delta_{j\ell} + A^{(3)} \delta_{i\ell} \delta_{j\epsilon}$$

$$\langle \dots \rangle_{\Omega} = d_1 d_2 d_3 d_4 \left[(\vec{e}_1 \cdot \vec{e}_2) (\vec{e}_3 \cdot \vec{e}_4) \underline{A^{(1)}} + (\vec{e}_1 \cdot \vec{e}_3) (\vec{e}_2 \cdot \vec{e}_4) \underline{A^{(2)}} + (\vec{e}_1 \cdot \vec{e}_4) (\vec{e}_2 \cdot \vec{e}_3) \underline{A^{(3)}} \right]$$

Invariants

$$\sum_{i,j} \langle u_i^{(1)} u_i^{(2)} u_j^{(3)} u_j^{(4)} \rangle_{\Omega} = \langle (\vec{u}_1 \cdot \vec{u}_1) (\vec{u}_3 \cdot \vec{u}_3) \rangle_{\Omega} = \underline{(\vec{u}_1 \cdot \vec{u}_1) (\vec{u}_3 \cdot \vec{u}_3)}$$

$$\begin{aligned} \sum_{i,j} \langle u_i^{(1)} u_i^{(2)} u_j^{(3)} u_j^{(4)} \rangle_{\Omega} &= \sum_{i,j} (A^{(1)} \delta_{ii} \delta_{jj} + A^{(2)} \delta_{ij} \delta_{ij} + A^{(3)} \delta_{ij} \delta_{ij}) \\ &= \underline{A^{(1)} 9 + A^{(2)} 3 + A^{(3)} 3} \end{aligned}$$

$$\sum_{i,j} \langle u_i^{(1)} u_j^{(2)} u_i^{(3)} u_j^{(4)} \rangle = \underline{(\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4)}$$

$$\begin{aligned} \sum_{i,j} \langle u_i^{(1)} u_j^{(2)} u_i^{(3)} u_j^{(4)} \rangle &= \sum_{i,j} A^{(1)} \delta_{ij} \delta_{ij} + A^{(2)} \delta_{ii} \delta_{jj} + A^{(3)} \delta_{ij} \delta_{ij} \\ &= \underline{A^{(1)} 3 + A^{(2)} 9 + A^{(3)} 3} \end{aligned}$$

$$\begin{aligned} \sum_{i,j} \langle u_i^{(1)} u_j^{(2)} u_j^{(3)} u_i^{(4)} \rangle &= \underline{(\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3)} \\ &= \underline{A^{(1)} 3 + A^{(2)} 3 + A^{(3)} 9} \end{aligned}$$

$$\begin{pmatrix} 9 & 3 & 3 \\ 3 & 9 & 3 \\ 3 & 3 & 9 \end{pmatrix} \begin{pmatrix} A^{(1)} \\ A^{(2)} \\ A^{(3)} \end{pmatrix} = \begin{pmatrix} (\vec{u}_1 \cdot \vec{u}_2)(\vec{u}_3 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3) \end{pmatrix}$$

$$\begin{pmatrix} A^{(1)} \\ A^{(2)} \\ A^{(3)} \end{pmatrix} = \begin{pmatrix} 9 & 3 & 3 \\ 3 & 9 & 3 \\ 3 & 3 & 9 \end{pmatrix}^{-1} \begin{pmatrix} (\vec{u}_1 \cdot \vec{u}_2)(\vec{u}_3 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3) \end{pmatrix}$$

$$\begin{pmatrix} 9 & 3 & 3 \\ 3 & 9 & 3 \\ 3 & 3 & 9 \end{pmatrix}^{-1} = \frac{1}{30} \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix}$$

$$\langle (\vec{d}_1 \cdot \vec{l}_1) (\vec{d}_2 \cdot \vec{l}_2) (\vec{d}_3 \cdot \vec{l}_3) (\vec{d}_4 \cdot \vec{l}_4) \rangle_{\Omega} =$$

$$= d_1 d_2 d_3 d_4 \begin{pmatrix} (\vec{d}_1 \cdot \vec{l}_1)(\vec{l}_1 \cdot \vec{l}_4) \\ (\vec{d}_1 \cdot \vec{l}_1)(\vec{l}_2 \cdot \vec{l}_4) \\ (\vec{d}_1 \cdot \vec{l}_1)(\vec{l}_3 \cdot \vec{l}_4) \end{pmatrix}^T \frac{1}{30} \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix} \begin{pmatrix} (\vec{d}_2 \cdot \vec{l}_2)(\vec{l}_2 \cdot \vec{l}_4) \\ (\vec{d}_2 \cdot \vec{l}_2)(\vec{l}_3 \cdot \vec{l}_4) \\ (\vec{d}_2 \cdot \vec{l}_2)(\vec{l}_1 \cdot \vec{l}_4) \end{pmatrix}$$

Examples

$$\vec{l} = \vec{l}_1 = \vec{l}_2 = \vec{l}_3 = \vec{l}_4$$

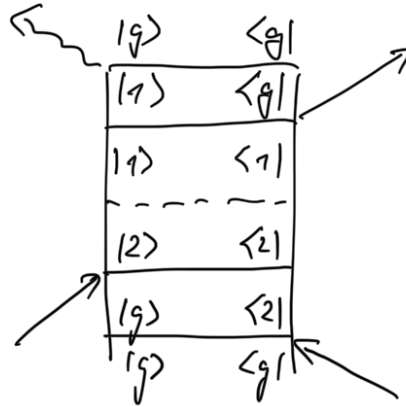
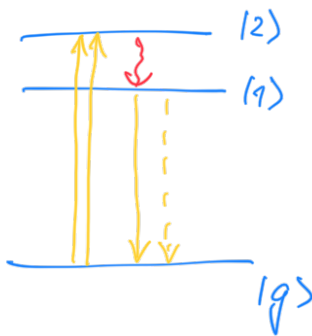
$$\langle (\vec{d}_1 \cdot \vec{l}) (\vec{d}_2 \cdot \vec{l}) (\vec{d}_3 \cdot \vec{l}) (\vec{d}_4 \cdot \vec{l}) \rangle_{\Omega} = \frac{d_1 d_2 d_3 d_4}{30} \begin{pmatrix} 2 & 2 & 2 \end{pmatrix} \begin{pmatrix} (\vec{d}_1 \cdot \vec{l})(\vec{l} \cdot \vec{l}) \\ \vdots \end{pmatrix}$$

$$= \frac{d_1 d_2 d_3 d_4}{15} \left[(\vec{d}_1 \cdot \vec{l})(\vec{d}_2 \cdot \vec{l}) + (\vec{d}_1 \cdot \vec{l})(\vec{d}_3 \cdot \vec{l}) + (\vec{d}_1 \cdot \vec{l})(\vec{d}_4 \cdot \vec{l}) + (\vec{d}_2 \cdot \vec{l})(\vec{d}_3 \cdot \vec{l}) + (\vec{d}_2 \cdot \vec{l})(\vec{d}_4 \cdot \vec{l}) + (\vec{d}_3 \cdot \vec{l})(\vec{d}_4 \cdot \vec{l}) \right]$$

if $\vec{d} = \vec{d}_1 = \vec{d}_2 = \vec{d}_3 = \vec{d}_4$

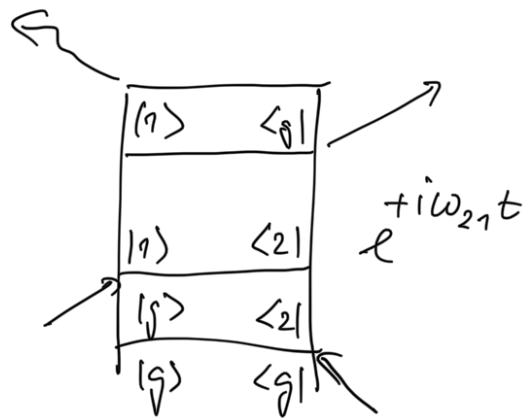
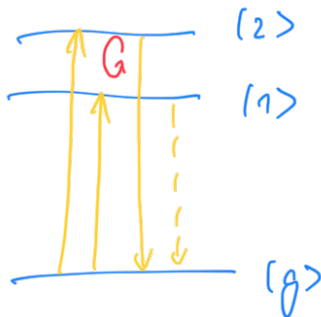
$$\langle (\vec{d} \cdot \vec{l})^4 \rangle_{\Omega} = \frac{d^4}{5}$$

Energy transfer



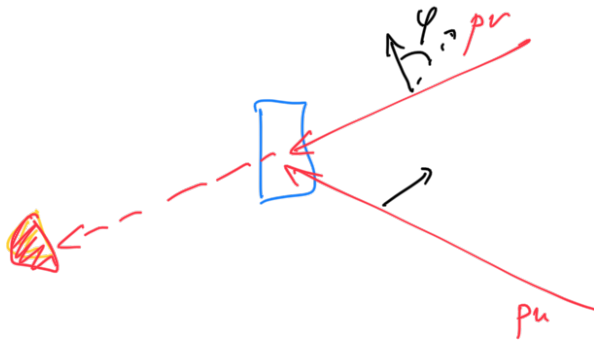
$$\langle \underbrace{(\vec{d}_2 \cdot \vec{e})}_{\text{red}} \underbrace{(\vec{d}_2 \cdot \vec{e})}_{\text{green}} \underbrace{(\vec{d}_1 \cdot \vec{e})}_{\text{blue}} \underbrace{(\vec{d}_1 \cdot \vec{e})}_{\text{red}} \rangle_{\Omega} = \frac{d_1^2 d_2^2}{15} \left[1 + 2(\vec{n}_2 \cdot \vec{n}_1)(\vec{n}_2 \cdot \vec{n}_1) \right]$$

Coherence

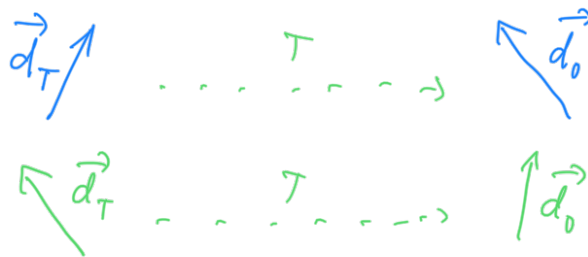


$$\langle (\vec{d}_2 \cdot \vec{e})(\vec{d}_1 \cdot \vec{e})(\vec{d}_2 \cdot \vec{e})(\vec{d}_1 \cdot \vec{e}) \rangle_{\Omega} = \frac{d_1^2 d_2^2}{15} \left[1 + 2(\vec{n}_1 \cdot \vec{n}_2)^2 \right]$$

Magic angle

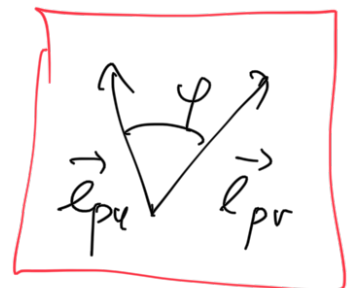


$$\psi = 54.7^\circ$$



Pump $\vec{l}_1 = \vec{l}_2 = \vec{l}_{pu}$

Probe $\vec{l}_3 = \vec{l}_4 = \vec{l}_{pr}$



$$\langle (\vec{d}_T \cdot \vec{l}_{pu}) (\vec{d}_T \cdot \vec{l}_{pu}) (\vec{d}_0 \cdot \vec{l}_{pr}) (\vec{d}_0 \cdot \vec{l}_{pr}) \rangle =$$

$$= \frac{d_T^2 d_0^2}{30} \begin{pmatrix} 1 & 2 \\ (\vec{l}_{pu} \cdot \vec{l}_{pr}) & \\ (\vec{l}_{pu} \cdot \vec{l}_{pr})^2 & \end{pmatrix}^T \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ (\vec{m}_T \cdot \vec{m}_0)^2 \\ (\vec{m}_T \cdot \vec{m}_0)^2 \end{pmatrix}$$

$$= \frac{d_T^2 d_0^2}{30} \begin{pmatrix} 1 \\ \cos^2 \varphi \\ \cos^2 \varphi \end{pmatrix}^T \begin{pmatrix} 4 - (\vec{u}_T^1 \cdot \vec{u}_0)^2 - (\vec{u}_T^2 \cdot \vec{u}_0)^2 \\ -1 + 4(\vec{u}_T^1 \cdot \vec{u}_0)^2 - (\vec{u}_T^1 \cdot \vec{u}_0)^2 \\ -1 - (\vec{u}_T^2 \cdot \vec{u}_0)^2 + 4(\vec{u}_T^2 \cdot \vec{u}_0)^2 \end{pmatrix}$$

$\Delta_{T0} = \vec{u}_T \cdot \vec{u}_0$

$$= \frac{d_T^2 d_0^2}{30} \left(4 - 2\Delta_{T0}^2 + \cos^2 \varphi (3\Delta_{T0}^2 - 1) + \cos^2 \varphi (3\Delta_{T0}^2 - 1) \right)$$

$$= \frac{d_T^2 d_0^2}{15} \left(2 - \Delta_{T0}^2 + \cos^2 \varphi (3\Delta_{T0}^2 - 1) \right) =$$

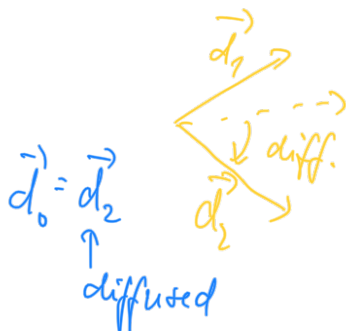
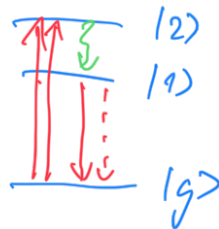
$$= \frac{d_T^2 d_0^2}{15} \left(\underbrace{[3\cos^2 \varphi - 1]}_{=0?} \Delta_{T0}^2 + 2 - \cos^2 \varphi \right)$$

$$3\cos^2 \varphi = 1$$

$$\cos^2 \varphi = \frac{1}{3}$$

$$\Rightarrow \varphi = \arccos\left(\frac{1}{\sqrt{3}}\right) = 54.7^\circ$$

Magic angle



Coherence

$$\begin{aligned}
 & \langle (\vec{d}_1 \cdot \vec{e}_{pu}) (\vec{d}_2 \cdot \vec{e}_{pu}) (\vec{d}_3 \cdot \vec{e}_{pr}) (\vec{d}_4 \cdot \vec{e}_{pr}) \rangle_{\Sigma} \\
 &= \frac{d_1 d_2 d_3 d_4}{30} \begin{pmatrix} 1 \\ (\vec{e}_{pu} \cdot \vec{e}_{pr})^2 \\ (\vec{e}_{pu} \cdot \vec{e}_{pr})^2 \end{pmatrix}^T \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix} \begin{pmatrix} (\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_2)(\vec{u}_3 \cdot \vec{u}_4) \\ (\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3) \end{pmatrix}
 \end{aligned}$$

$\Delta_1 = (\vec{u}_1 \cdot \vec{u}_3)(\vec{u}_2 \cdot \vec{u}_4)$
 $\Delta_2 = (\vec{u}_1 \cdot \vec{u}_4)(\vec{u}_2 \cdot \vec{u}_3)$
 $\Delta = (\vec{u}_1 \cdot \vec{u}_2)(\vec{u}_3 \cdot \vec{u}_4)$

subject to diffusion
 — have to be eliminated

$$\langle \dots \rangle_{\Sigma} = \Delta \frac{d_1 d_2 d_3 d_4}{30} \begin{pmatrix} 1 \\ \cos^2 \varphi \\ \cos^2 \varphi \end{pmatrix}^T \begin{pmatrix} 4 & -1 & -1 \\ -1 & 4 & -1 \\ -1 & -1 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ \frac{\Delta_1}{\Delta} \\ \frac{\Delta_2}{\Delta} \end{pmatrix}$$

$$= \frac{\Delta d_1 d_2 d_3 d_4}{30} \begin{pmatrix} 1 \\ \cos^2 \varphi \\ \cos^2 \varphi \end{pmatrix}^T \begin{pmatrix} 4 - \frac{\Delta_1 + \Delta_2}{\Delta} \\ -1 + 4 \frac{\Delta_1}{\Delta} - \frac{\Delta_2}{\Delta} \\ -1 - \frac{\Delta_1}{\Delta} + 4 \frac{\Delta_2}{\Delta} \end{pmatrix}$$

$$= \Delta \frac{d_1 d_2 d_3 d_4}{30} \left(4 - \frac{\Delta_1 + \Delta_2}{\Delta} + \left(\frac{4\Delta_1 - \Delta_2}{\Delta} - 1 \right) \cos^2 \varphi + \left(\frac{4\Delta_2 - \Delta_1}{\Delta} - 1 \right) \cos^2 \varphi \right)$$

$$= \Delta \frac{d_1 d_2 d_3 d_4}{30} \left(4 - 2\cos^2 \varphi + \frac{\Delta_1 + \Delta_2}{\Delta} (2\cos^2 \varphi - 1) \right)$$

magic angle work generally!

Special case of even-order spectroscopies

$$\langle (\vec{d}_1 \cdot \vec{e}_1)(\vec{d}_2 \cdot \vec{e}_2) \rangle_{\Omega} \neq 0$$

$$\langle (\vec{d}_1 \cdot \vec{e}_1)(\vec{d}_2 \cdot \vec{e}_2)(\vec{d}_3 \cdot \vec{e}_3)(\vec{d}_4 \cdot \vec{e}_4) \rangle_{\Omega} \neq 0$$

$$\langle (\vec{d}_1 \cdot \vec{e}) \rangle_{\Omega} = 0$$

$$\langle (\vec{d}_1 \cdot \vec{e})(\vec{d}_2 \cdot \vec{e})(\vec{d}_3 \cdot \vec{e}) \rangle_{\Omega} = 0 \quad !$$

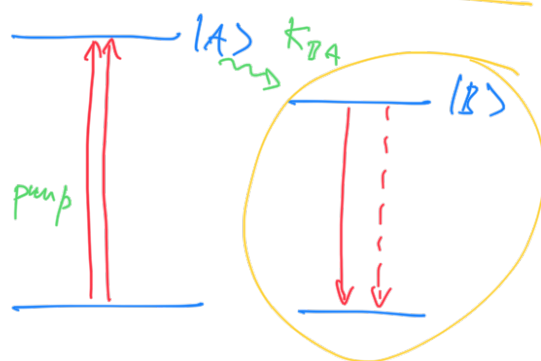
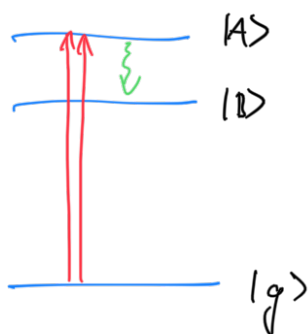

$$\vec{k}_S = \vec{k}_1 + \vec{k}_2 \rightarrow \omega_S = \omega_1 + \omega_2$$

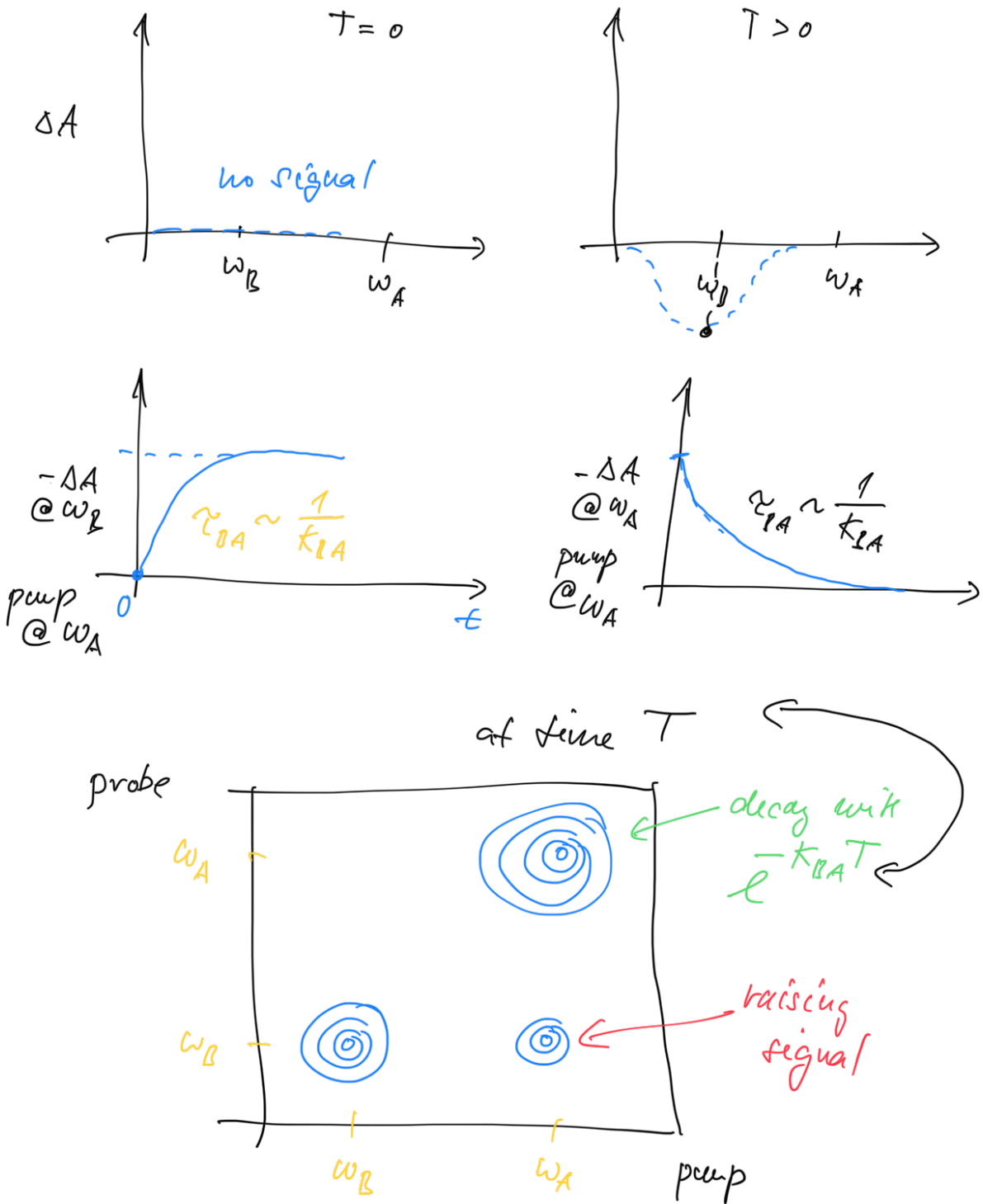
$$e^{i(\vec{k}_1 + \vec{k}_2) \cdot \vec{r}} = e^{i(\omega_1 + \omega_2)t}$$

We cannot produce second harmonic (sum frequency) in an isotropic sample.

Monitoring energy transfer processes

by pump-probe spectroscopy





Probing and pumping with frequency resolution - $\Delta\omega$

→ length of the pulse $\equiv$ time resolution
scales with $\frac{1}{\Delta\omega}$